

## **J&P Technologies Joins TASC Team on \$133.9 Million NASA Contract**

**December, 2011** – J&P Technologies is among expert companies to join the TASC, Inc. team that has been awarded a five-year contract worth up to \$133.9 million to provide highly specialized system software services to NASA. Under the contract, TASC and its partners will provide independent verification and validation, software assurance, research and development and technical quality monitoring.

“Our goal is to ensure that NASA’s complex software products meet the overall needs of each program and fulfill the requirements of each phase of its life cycle,” says Jennifer Lewis – J&P’s President. “Our expertise in assuring the safety of Human Space Flight and extensive knowledge of Flight Systems, in particular the development of Flight and Ground Support Software, are key to J&P meeting program objectives.”

J&P Technologies is Houston-based small business, established in 1997 to provide contract services for the development, assessment, and support of integrated flight systems, scientific computing, and complex control systems, specifically in the aerospace and biomedical industries. Our highly-trained professionals have extensive experience in developing, integrating, delivering, and sustaining major human rated systems / projects at NASA and are familiar with complex development and delivery processes, as well as system support requirements. Backed by over thirty years experience in System Engineering, Safety and Mission Assurance, Software Architecture, Software Development, and System Integration/Test, J&P Technologies offers high-quality services for small and large-scale systems in both the commercial and government markets.

Founded in 1966, TASC, Inc., provides advanced systems engineering, integration and decision-support services to the Intelligence Community, Department of Defense and civilian agencies of the federal government. With about 5,000 employees in 40 locations, TASC generates \$1.5 billion in annual revenue.